

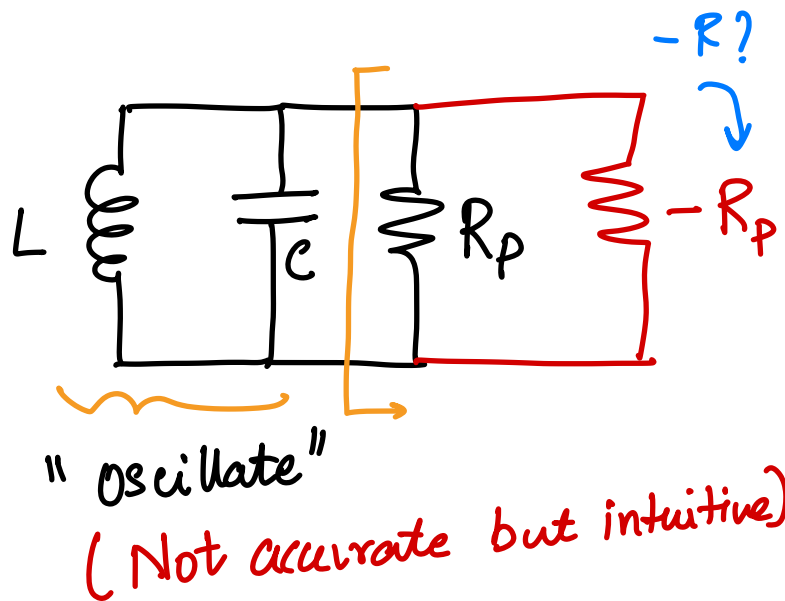
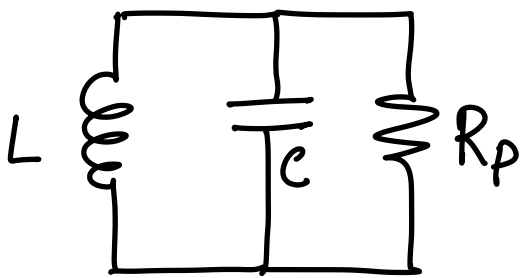


Cross Coupled Oscillator - Theory

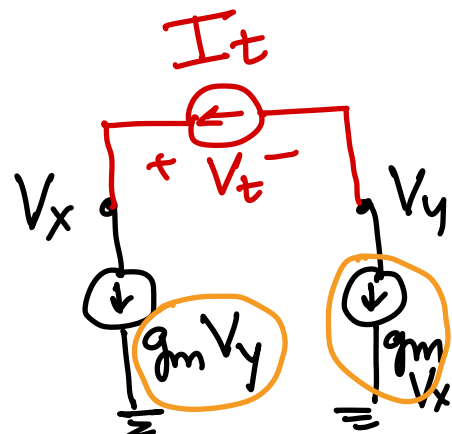
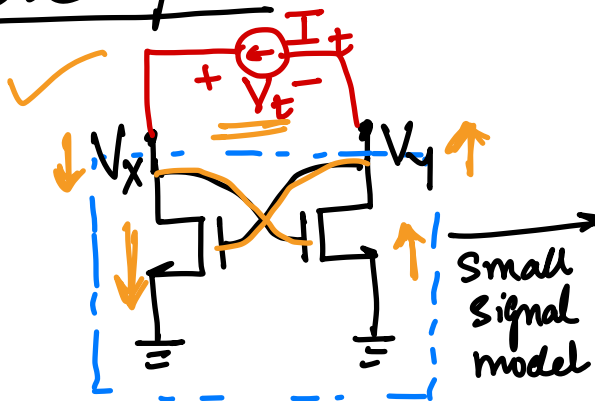
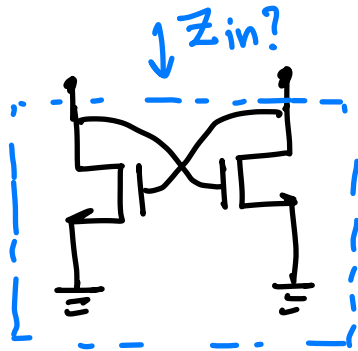
(I) Start-up condition

- ✓ 1) Barkhausen Criteria. → Ring oscillators.
- ✓ 2) Negative resistance. → LC oscillators.

Note: Both of these criteria are mathematically wrong. (Why?) But they provide some intuition & we only use them to study the startup condition.



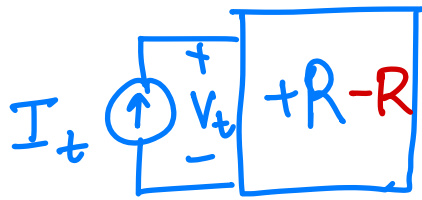
(II) Cross-coupled pair



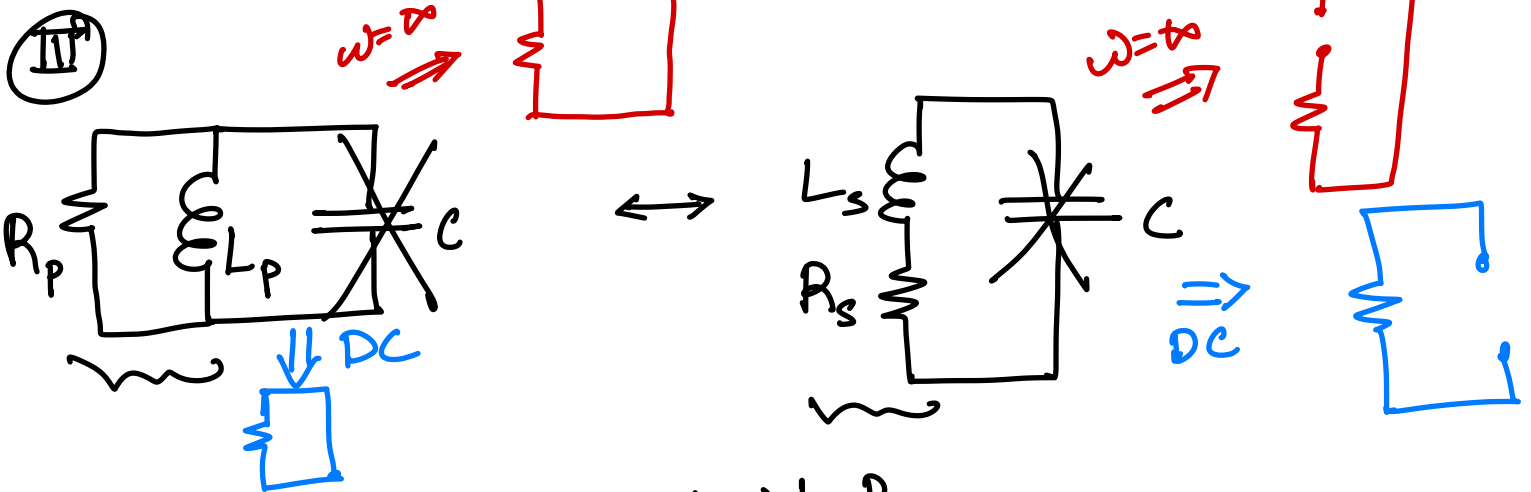
$$V_t = V_x - V_y ; I_t = g_m V_y ; V_x = -V_y$$

$$\frac{V_t}{I_t} = Z_{in} = -\frac{2}{g_m}$$

Negative "small-signal" Resistance.



$I_t \uparrow \Rightarrow \partial I_t$ is +ve
 $V_t \uparrow \Rightarrow \partial V_t$ is +ve.
 $V_t \downarrow \Rightarrow \partial V_t$ is -ve.



$$j\omega L_s + R_s = \frac{j\omega L_p R_p}{j\omega L_p + R_p}$$

$$L_p = \frac{R_s^2}{L_s \omega^2} + L_s$$

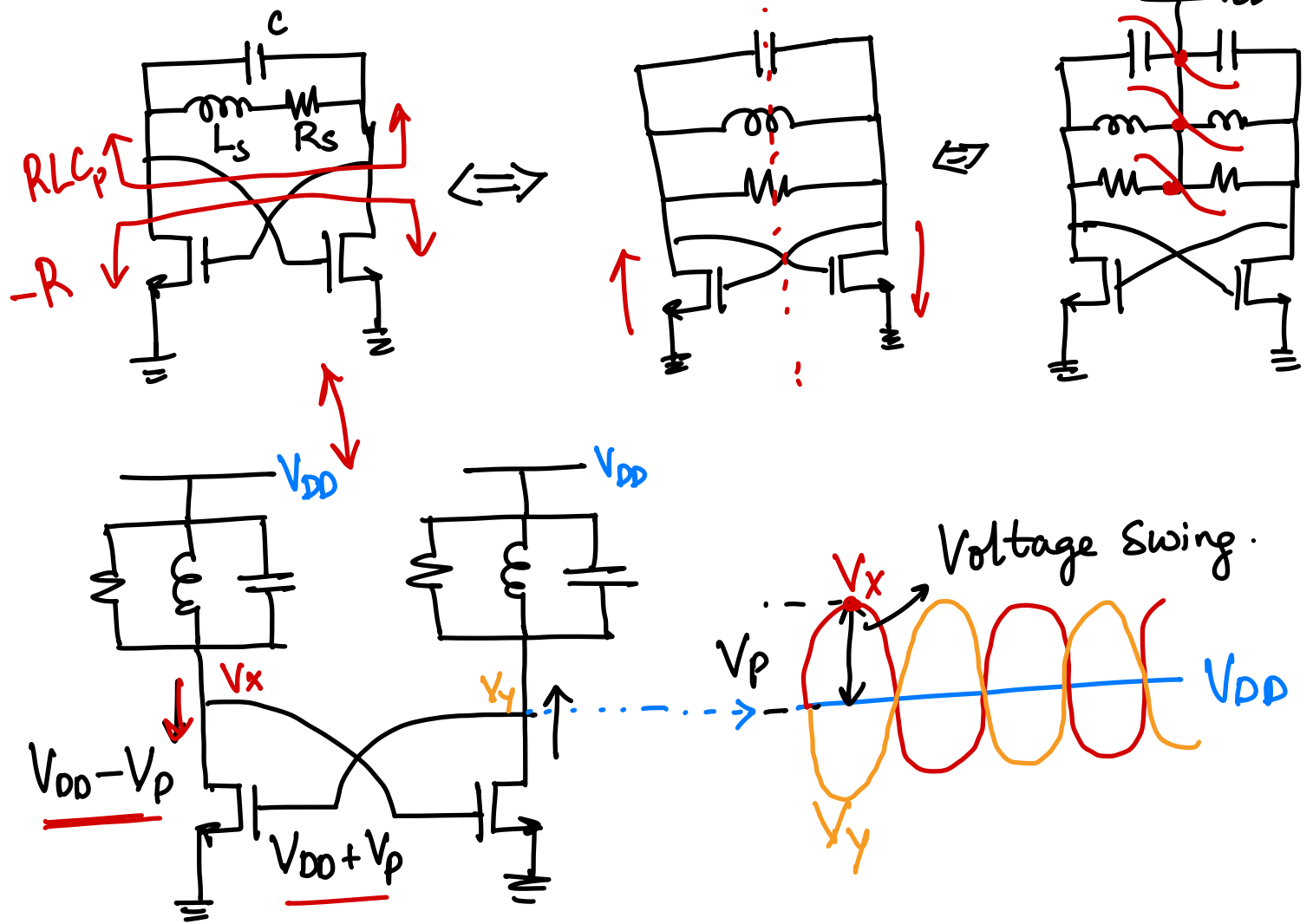
$\ll 1$

$$Q_L = \frac{L_s \omega}{R_s}$$

$$\Rightarrow L_p = L_s \quad ; \quad R_p \approx \frac{L_s^2 \omega^2}{R_s \uparrow}$$

Note: This equivalence is narrow band.

IV Cross Coupled Oscillator



$$V_{DS} > V_{GS} - V_{TH} \quad \} \quad V_{DS} = V_{GS} - V_{TH}$$

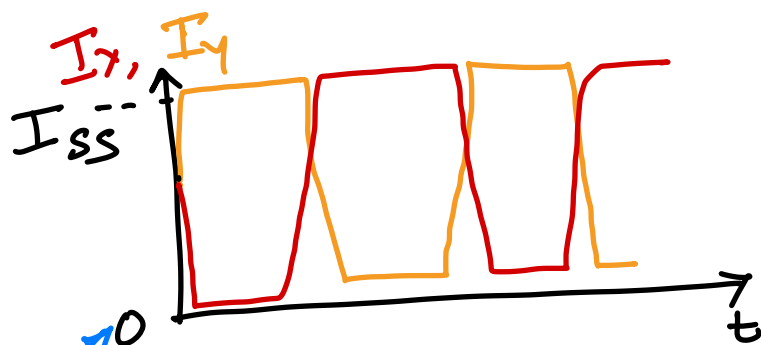
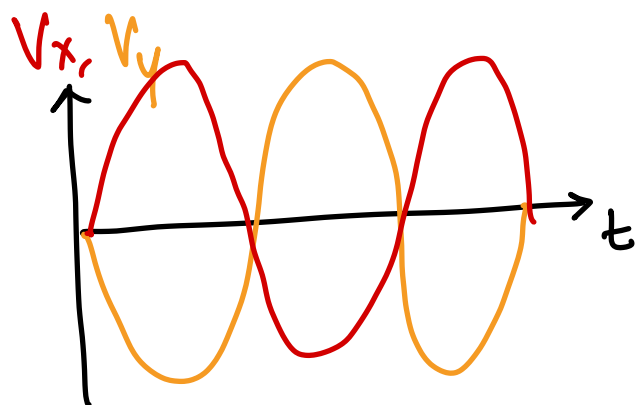
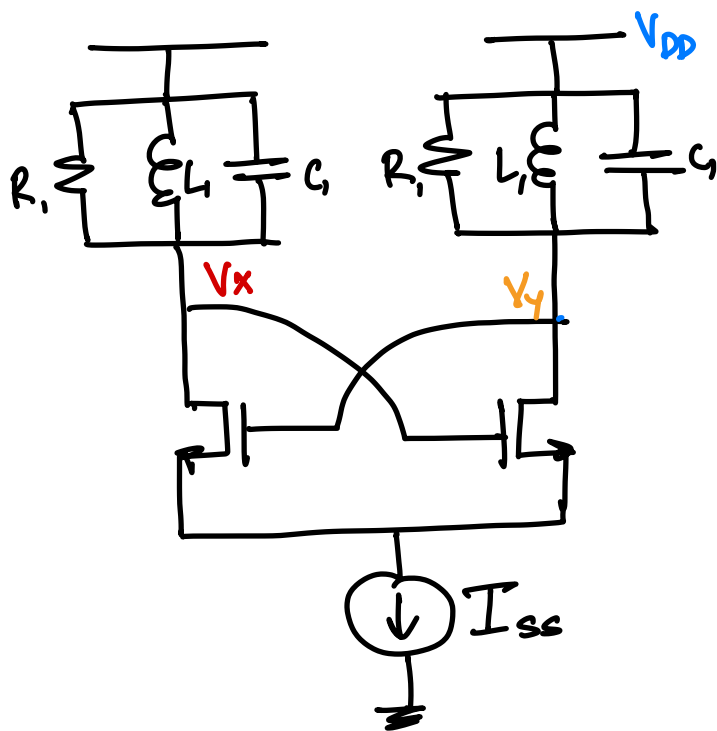
To avoid Triode

$$V_{pp} = V_{TH}$$

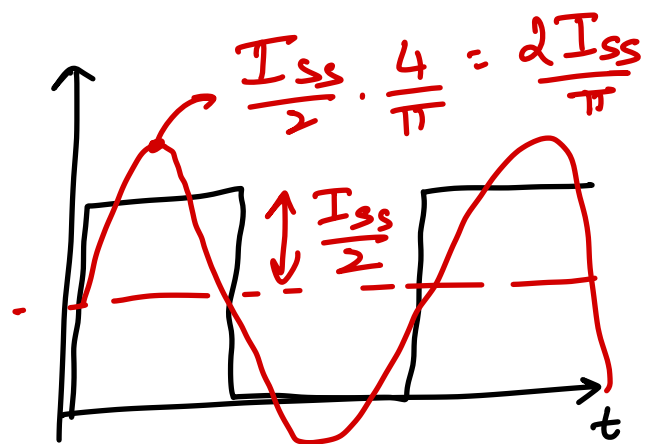
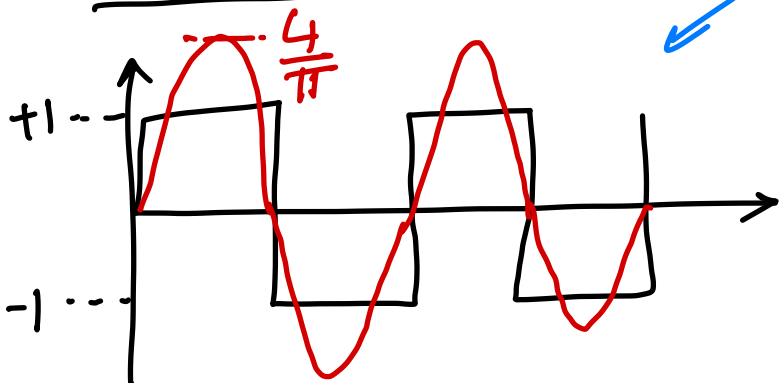
$$V_D - V_G = -V_{TH}$$

$$(V_{DD} - V_p) - (V_{DD} + V_p) = -V_{TH}$$

$$\Rightarrow V_p = \frac{V_{TH}}{2}$$



What is V_p ?



$$\Rightarrow V_p = \frac{2 I_{SS} R_p}{\pi}$$

$$V_{pp}^{diff} = \frac{8 I_{SS} R_p}{\pi}$$

Assuming I is a square wave.

$(g_m R_p \gg 2) \rightarrow$ Rule of Thumb.

Design Procedure (Algorithmic approach)
(Specified P_{DC} & low phase constraint).

1) Set P_{oc} & $V_p = \frac{V_{TH}}{2}$

2) $I_{ss} = \frac{P_{oc}}{V_{DD}}$

$V_{pp} = V_{TH} = \frac{4 I_{ss} R_p}{\pi}$

$\Rightarrow R_p = \frac{\pi V_{DD} V_{TH}}{4 P_{oc}}$ ←

3) $Q_L = \frac{R_p}{L_1 \omega_0} \Rightarrow L_1 = \frac{R_p}{Q_L \omega_0}$

→ Predetermined by process & ω_0 .
(8-10)

$C_1 = \frac{1}{\omega_0^2 L_1}$

→ Also includes parasitic caps.

4) Choose $\frac{W}{L}$ to get full current steering,
i.e. Square wave current steering; $V_{pp} = \frac{4}{\pi} I_{ss} R_p$
(Also look at $J_D = \frac{I_{os}}{W L}$)

5) Simulate & tune C_1 to get ω_0 . Look at the
PN performance \Rightarrow Increase power budget if needed.

(Taken from Behzad Razavi's PLL book).