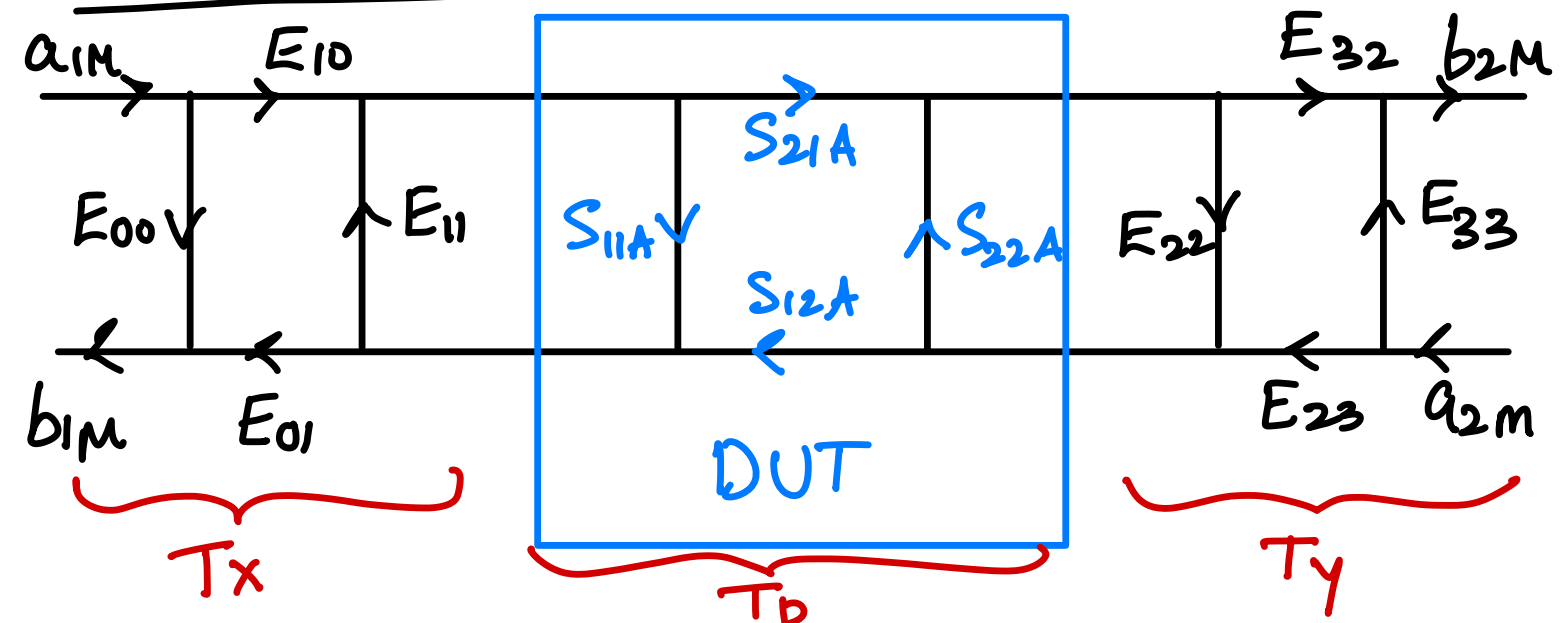




TRL Calibration (Thru-Reflect-Line).

8-Term Error Model



Transmission Matrices

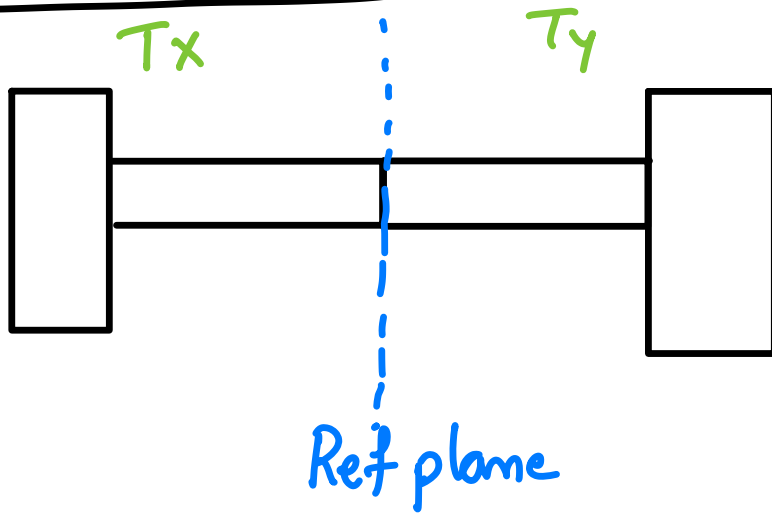
$$T = \frac{1}{S_{21}} \begin{bmatrix} S_{12}S_{21} - S_{11}S_{22} & S_{11} \\ -S_{22} & 1 \end{bmatrix}$$

$$S = \frac{1}{T_{22}} \begin{bmatrix} T_{12} & T_{11}T_{22} - T_{12}T_{21} \\ 1 & -T_{21} \end{bmatrix}$$

$$T_M = T_x T_D T_y$$

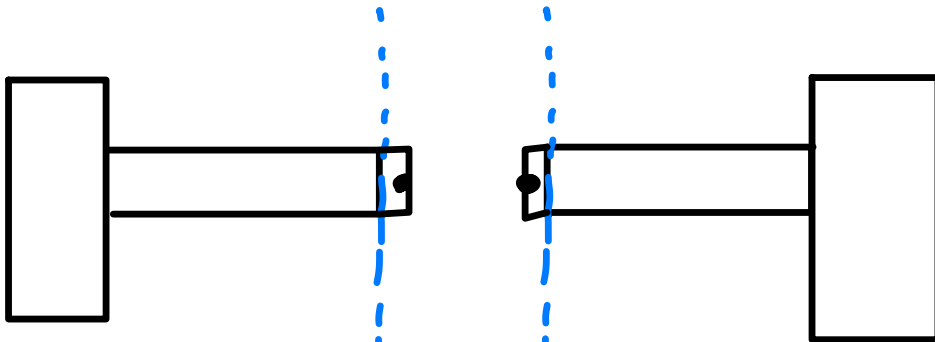
TRL Calibration Standards

Thru :



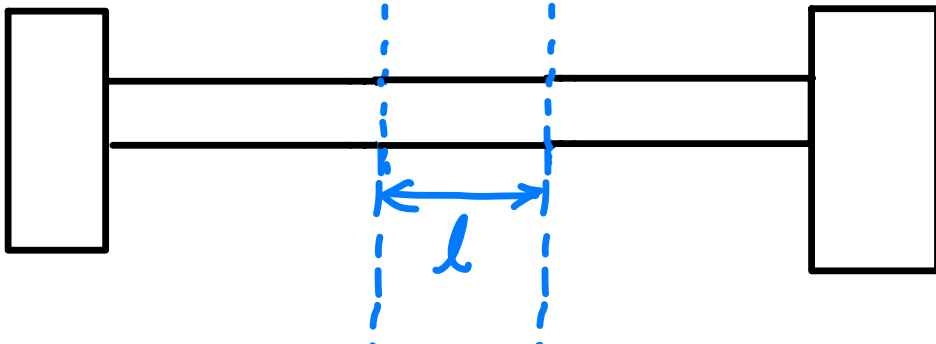
$$T_T = T_x T_y$$

Reflect :



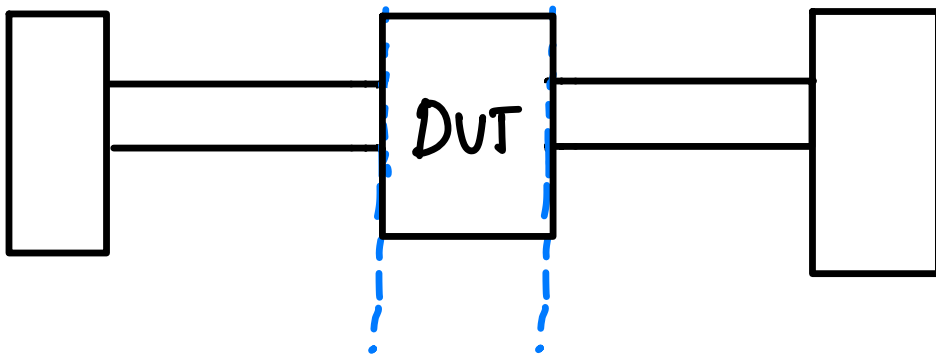
$$S_{11} = \Gamma_R$$
$$S_{22} = \Gamma_R$$

Line



$$T_L = T_x \Delta T_y$$
$$\Delta = \begin{bmatrix} e^{-\gamma l} & 0 \\ 0 & e^{+\gamma l} \end{bmatrix}$$

DUT



$$T_M$$

TRL model

$$M = T_L T_T^{-1} = T_x \Lambda T_y T_y^{-1} T_x^{-1}$$

$$M = T_x \Lambda T_x^{-1}$$

⇒ Eigenvalues of M are

$$\lambda_1 = e^{-\gamma l}$$

$$\lambda_2 = e^{+\gamma l}$$

$$\Rightarrow \gamma = \frac{1}{2l} \ln \left(\frac{\lambda_2}{\lambda_1} \right) \quad \left(\text{Approx. knowledge of } \gamma \text{ is needed to correctly assign } \lambda_1, \lambda_2 \right)$$

$$M T_x = T_x \Lambda$$

$$S_x = \begin{bmatrix} E_{00} & E_{01} \\ E_{10} & E_{11} \end{bmatrix}$$

$$\Rightarrow T_x = \frac{1}{E_{10}} \begin{bmatrix} -(E_{00}E_{11} - E_{01}E_{10}) & E_{00} \\ -E_{11} & 1 \end{bmatrix}$$

$$\begin{bmatrix} M_{11} & M_{12} \\ M_{21} & M_{22} \end{bmatrix} \begin{bmatrix} -\frac{(E_{00}E_{11} - E_{01}E_{10})}{E_{10}} & \frac{E_{00}}{E_{10}} \\ -\frac{E_{11}}{E_{10}} & \frac{1}{E_{10}} \end{bmatrix} = \begin{bmatrix} & \\ & \text{"} \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

↓

$$M_{11} E_{00} + M_{12} = E_{00} \lambda_2$$

$$\Rightarrow E_{00} = \frac{M_{12}}{\lambda_2 - M_{11}}$$

$$\frac{E_{01}E_{10}}{E_{11}} = \frac{M_{12}}{\lambda_2 - M_{11}} - \frac{M_{12}}{\lambda_1 - M_{11}}$$

$$M' = T_T^{-1} T_L$$

$$E_{33} = \frac{M_{21}'}{\lambda_2 - M_{22}'}$$

$$\frac{E_{23} E_{32}}{E_{22}} = \frac{M_{21}'}{\lambda_2 - M_{22}'} - \frac{M_{21}'}{\lambda_1 - M_{22}'}$$

▷ S_{11}, S_{22} of Thru Measurement.

$$S_{11,T}^m = E_{00} + \frac{E_{01} E_{10} E_{22}}{1 - E_{11} E_{22}}$$

$$= E_{00} + \frac{\frac{E_{01} E_{10}}{E_{11}}}{\frac{1}{E_{11} E_{22}} - 1}$$

$$\Rightarrow E_{11} E_{22} = \frac{S_{11,T}^m - E_{00}}{\left(\frac{E_{01} E_{10}}{E_{11}} \right) + S_{11,T}^m - E_{00}}$$

Using Γ_R

$$\begin{aligned}\Gamma_R &= \frac{\Gamma_{R_1}^M - E_{00}}{E_{11}(\Gamma_{R_1}^M - E_{00}) + E_{01}E_{10}} \\ &= \frac{\Gamma_{R_2}^M - E_{33}}{E_{22}(\Gamma_{R_2}^M - E_{33}) + E_{32}E_{23}}\end{aligned}$$

$$\frac{E_{11}}{E_{22}} = \left[\frac{\Gamma_{R_1}^M - E_{00}}{(\Gamma_{R_1}^M - E_{00}) + \frac{E_{01}E_{10}}{E_{11}}} \right] \left[\frac{\Gamma_{R_2}^M - E_{33}}{(\Gamma_{R_2}^M - E_{33}) + \frac{E_{23}E_{32}}{E_{22}}} \right]^{-1}$$

Remove sign ambiguity of E_{11}, E_{22} by checking Γ_R .

→ We now have $E_{00}, E_{11}, E_{01}E_{10}$ &
 $E_{22}, E_{33}, E_{23}E_{32}$.

We also got Γ_R, γ as a bonus.

Inversion

$$T_X^{-1} = \frac{1}{E_{01} E_{10}^2} \begin{bmatrix} 1 & -E_{00} \\ E_{11} & -(E_{00}E_{11} - E_{01}E_{10}) \end{bmatrix}$$

$$T_Y^{-1} = \frac{1}{E_{23} E_{32}^2} \begin{bmatrix} 1 & -E_{22} \\ E_{33} & -(E_{22}E_{33} - E_{23}E_{32}) \end{bmatrix}$$

$$S_{21,T}^M = \frac{E_{10} E_{32}}{1 - E_{11} E_{22}}$$

$$T_D = \frac{1}{E_{01} E_{10}} \cdot \frac{1}{E_{23} E_{32}} \cdot \frac{1}{E_{10} E_{32}}$$

$$\begin{bmatrix} 1 & -E_{00} \\ E_{11} & -(E_{00}E_{11} - E_{01}E_{10}) \end{bmatrix} T_M \begin{bmatrix} 1 & -E_{22} \\ E_{33} & -(E_{22}E_{33} - E_{23}E_{32}) \end{bmatrix}$$

Limitations

- ① Line impedance
- ② BW limited (Thru will be 180° from line)
[Multiline TRL calibration]

③ Γ is symmetric.